



Design of Nano-Photonic devices

Achim Schädle
Zuse Institute Berlin

DFG Research Center MATHEON
Mathematics for key technologies



Application Area D: Circuits simulation and opto-electronic devices

- ▷ Circuits simulation
- ▷ Modelling of active optical devices
- ▷ Simulation of passive optical devices
- ▷ Chip design verification



Projects: D9, D15

Heads: P. Deuflhard, F. Schmidt

Staff: B. Kettner, T. Pollok, A. Schädle

Computation of electromagnetic fields in three space dimensions.

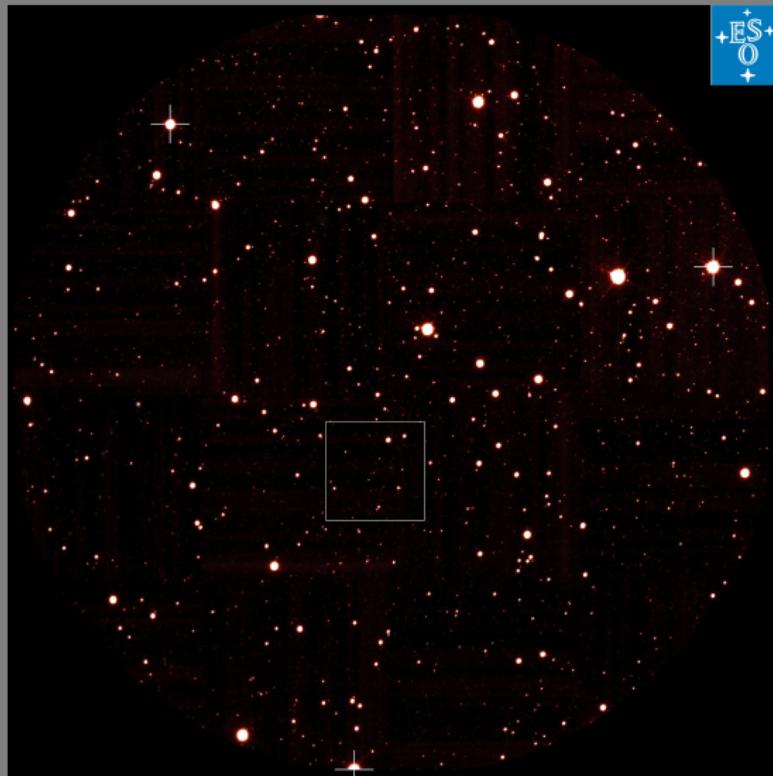
Wavelength of light: $\lambda = 100 - 1000\text{nm}$

Structure size: $10 - 100\text{nm} = 10 - 100 \cdot 10^{-9}\text{m}$

- ▷ Photonic crystals
- ▷ Photonic crystal fibres
- ▷ Metamaterials
- ▷ Lithography masks
- ▷ Photonic cavities



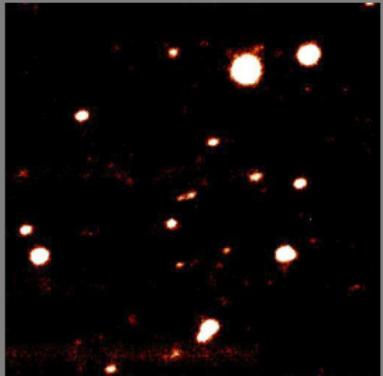
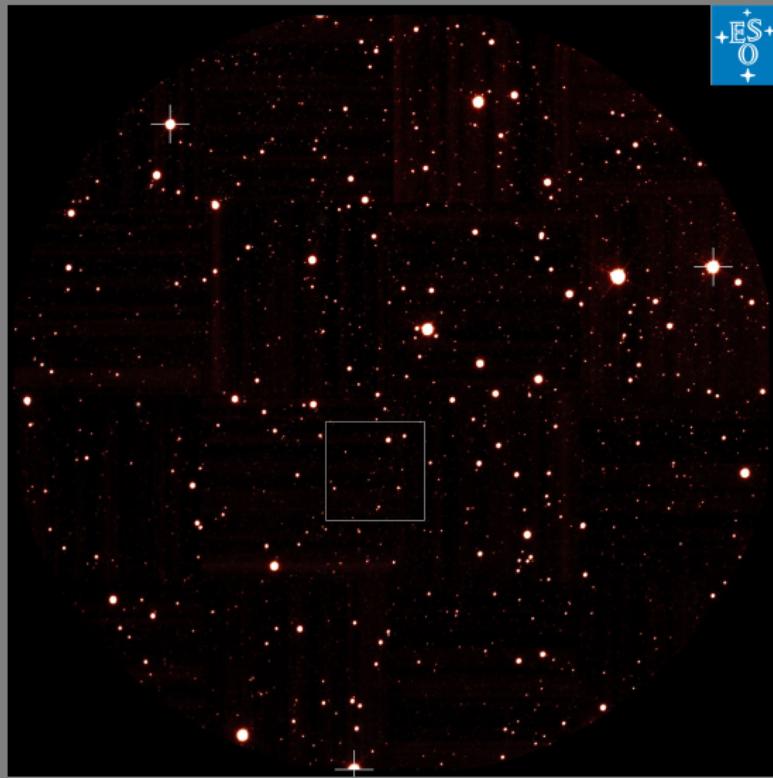
Adaptive optics



Omega Centauri, European Southern Observatory (ESO)



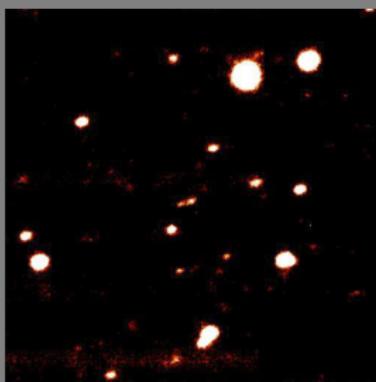
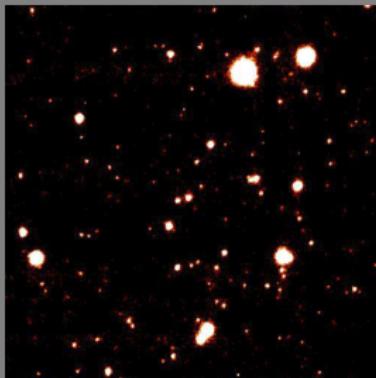
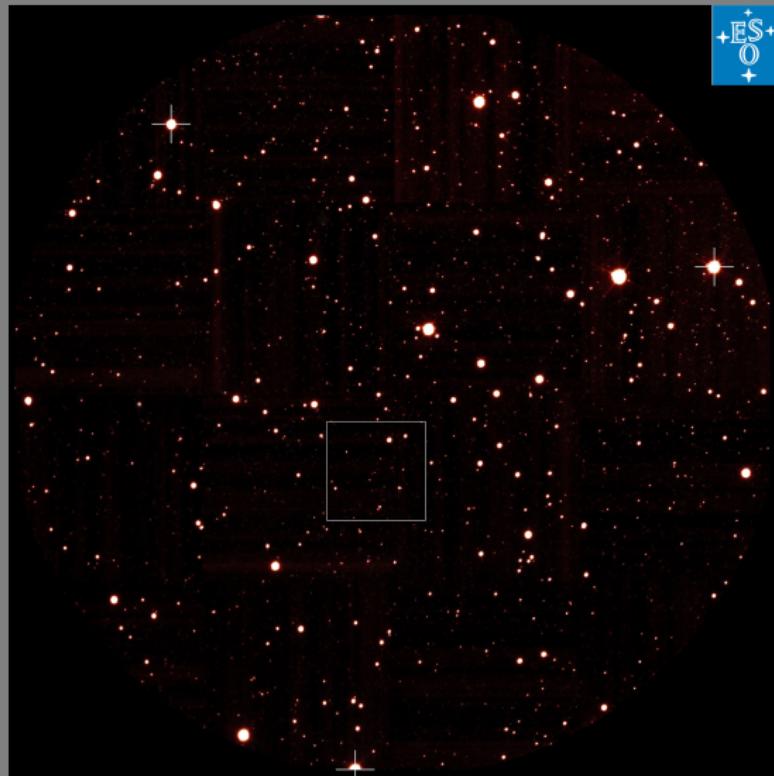
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Adaptive optics



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Laser Guide Star



Photograph: Y. Beletsky



Guide a laser beam to the telescope

- ▷ Transport very high energy at $\lambda = 589.2\text{nm}$
- ▷ Reduce radiation loops



Photonic crystal fiber

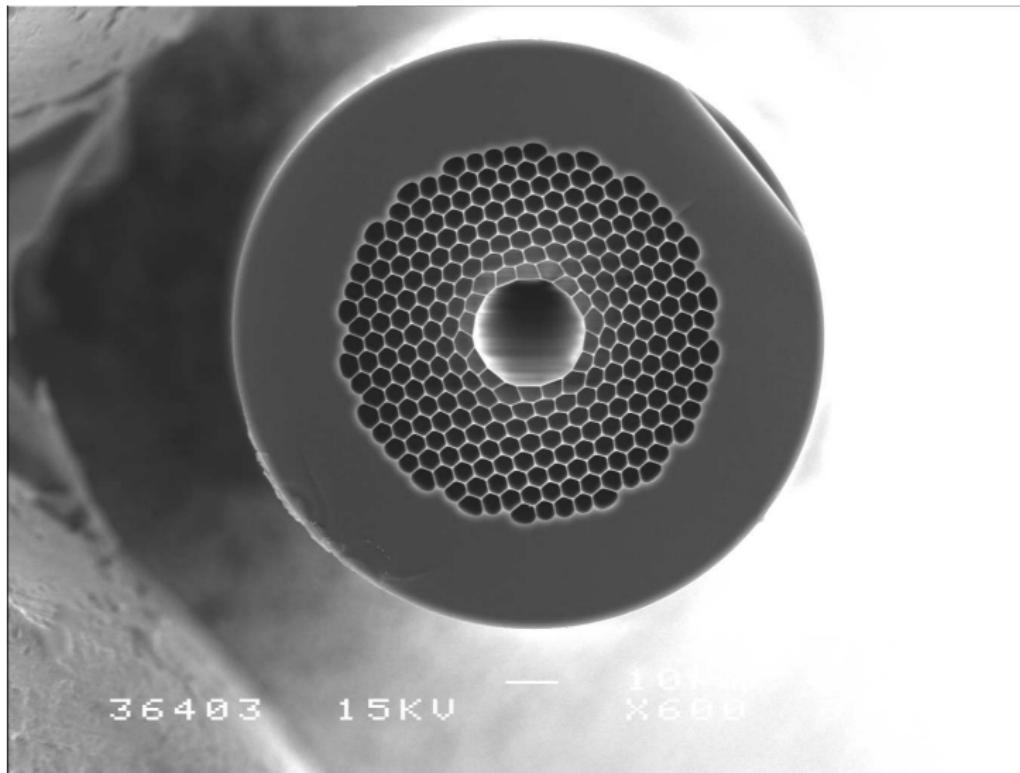


Image courtesy: Crystal Fibre A/S, Denmark.

$$\mathbf{H}(r, t) = \exp(i\omega t)\mathbf{H}(r)$$

Time harmonic Maxwell's equations

$$\nabla \times \epsilon(r)^{-1} \nabla \times \mathbf{H}(r) + \mu(r) \omega^2 \mathbf{H}(r) = 0$$

+ boundary conditions + divergence condition



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Propagating mode

$$\mathbf{H}(r) = \mathbf{H}(x, y, z) = \exp(ik_z z)\mathbf{H}(x, y)$$



$$\mathbf{H}(x, y) = \begin{bmatrix} H_x(x, y) \\ H_y(x, y) \\ H_z(x, y) \end{bmatrix} = \begin{bmatrix} \mathbf{H}_\perp \\ H_z \end{bmatrix}$$

Trick: $\tilde{H}_z = k_z H_z$

$$\begin{bmatrix} P \nabla_\perp \epsilon^{-1} \nabla_\perp \cdot P - \omega^2 \mu & -iP\epsilon^{-1}P\nabla_\perp \\ 0 & \nabla_\perp \cdot P\epsilon^{-1}P\nabla_\perp - \omega^2 \mu \end{bmatrix} \begin{bmatrix} \mathbf{H}_\perp \\ \tilde{H}_z \end{bmatrix}$$
$$= k_z^2 \begin{bmatrix} P\epsilon^{-1}P & 0 \\ i\nabla_\perp \cdot P\epsilon^{-1}P & 0 \end{bmatrix} \begin{bmatrix} \mathbf{H}_\perp \\ \tilde{H}_z \end{bmatrix}$$

with $P = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$, $\nabla_\perp = \begin{bmatrix} \partial_x \\ \partial_y \end{bmatrix}$



General eigenvalue problem for k_z with singular B

$$A \begin{bmatrix} H_{\perp} \\ \tilde{H}_z \end{bmatrix} = k_z^2 B \begin{bmatrix} H_{\perp} \\ \tilde{H}_z \end{bmatrix},$$



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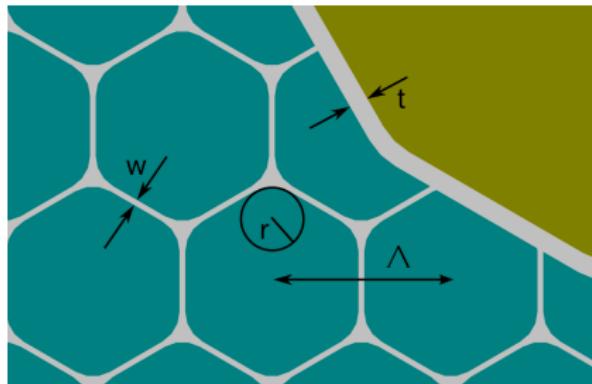
$\Im(k_z) \propto$ energy flux across boundary



- ▷ High order curl conforming finite elements
- ▷ Adaptive grid refinement
- ▷ Transparent boundary conditions (PML, Pole condition)



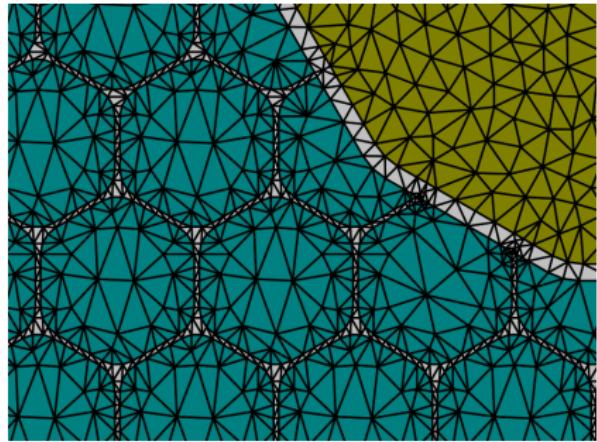
Geometry and Triangulation

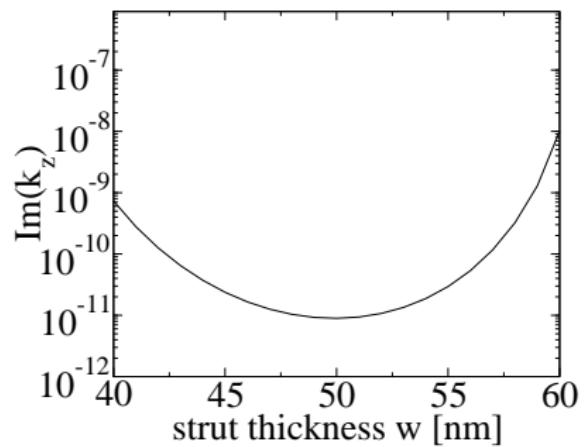
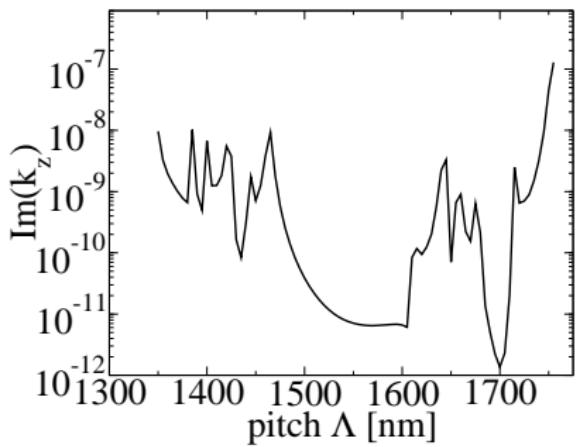


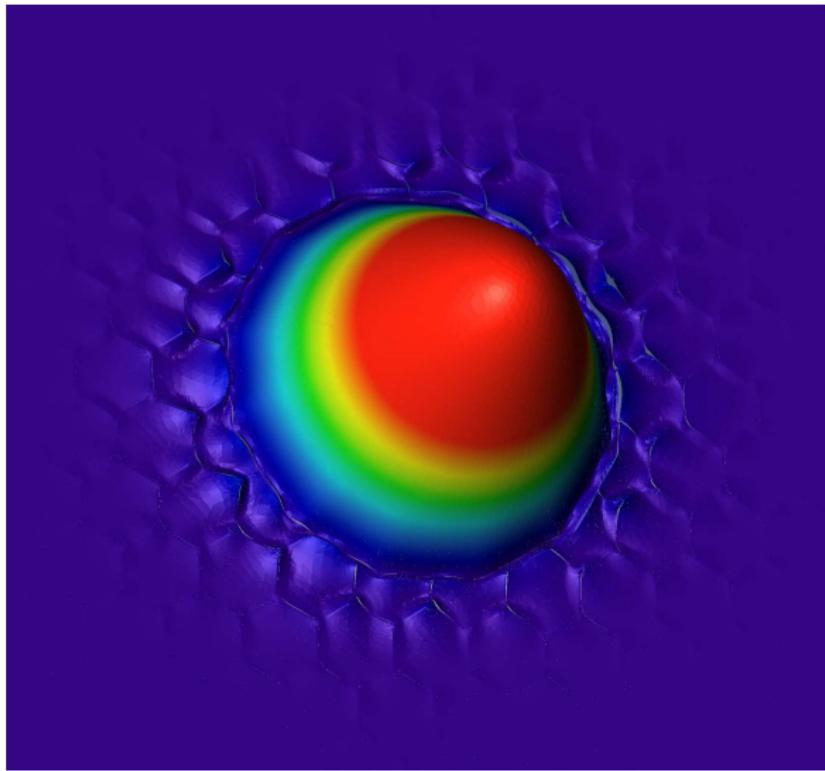
Geometry cut out

Parameters to be optimized

Finite element grid







Intensity of the field



Transparent boundary conditions

2D scalar case (Helmholtz equation)

$$\Delta u(x, y) + k^2(x, y)u(x, y) = f, \quad (x, y) \in \mathbb{R}^2$$

$$\lim_{|r| \rightarrow \infty} \sqrt{r}(\partial_r u - iku) = 0, \quad r = \frac{(x, y)}{\|(x, y)\|}$$

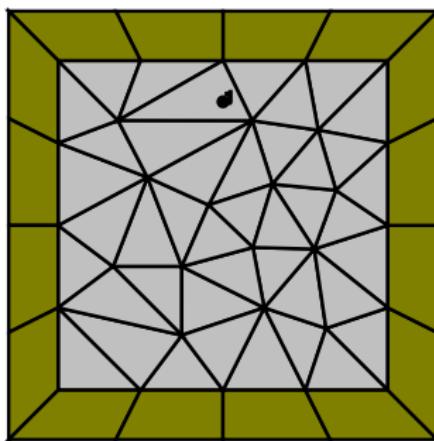


Transparent boundary conditions

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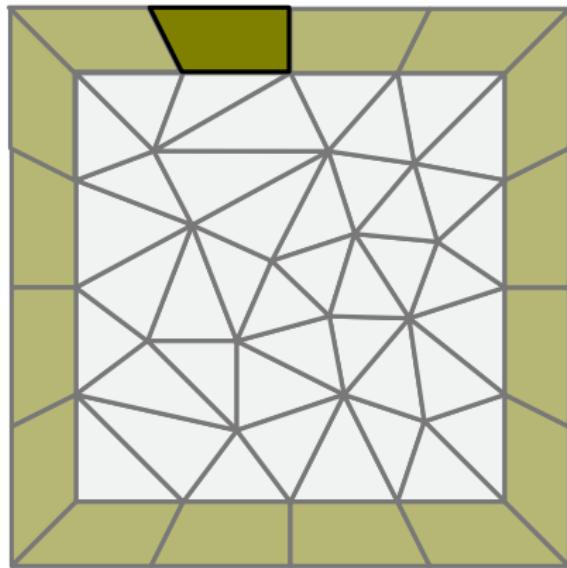
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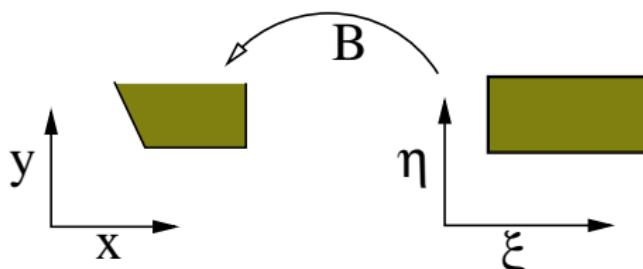


Transformation unit rectangle



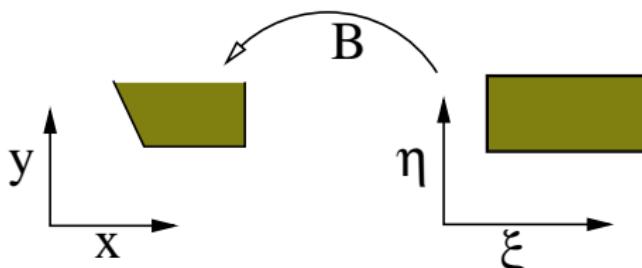


Transformation unit rectangle





Transformation unit rectangle



$$J_B = \begin{pmatrix} 1 & 0 \\ \eta b - a & h_\eta + \xi b \end{pmatrix}; \quad |J_B| = h_\eta + \xi b$$

$$\int_{prism} \nabla u(x, y) \cdot \nabla \phi(x, y) dx dy =$$
$$\int_0^1 \int_0^\infty \left(J_B^{-T} \nabla_{\xi, \eta} \tilde{u}(\xi, \eta) \right) \cdot J_B^{-T} \nabla_{\xi, \eta} \tilde{\phi}(\xi, \eta) |J_B| d\xi d\eta$$



Exponential test function

$$\int_{prism} \nabla u(x, y) \cdot \nabla \phi(x, y) dx dy = \\ \int_0^1 \int_0^\infty \left(J_B^{-T} \nabla_{\xi, \eta} u(\xi, \eta) \right) \cdot J_B^{-T} \nabla_{\xi, \eta} \phi(\xi, \eta) |J_B| d\xi d\eta$$

$$\phi(\xi, \eta) = \phi(\eta) \exp(-s\xi)$$



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Laplace transform of u in distance variable ξ

$$U(\eta, s) = \int_0^\infty u(\eta, \xi) \exp(-s\xi) d\xi$$



$$\begin{aligned} & \int_0^\infty \left(J_B^{-T} \nabla_{\xi,\eta} u(\xi, \eta) \right) \cdot J_B^{-T} \nabla_{\xi,\eta} \phi(\xi, \eta) |J_B| d\xi \\ &= \int_0^\infty (h_\eta + \xi b) \partial_\xi \phi \partial_\xi u \\ &\quad - (\eta b - a) \partial_\eta \phi \partial_\xi u \\ &\quad - (\eta b - a) \partial_\xi \phi \partial_\eta u \\ &\quad + \frac{1 + (\eta b - a)^2}{(h_\eta + \xi b)} \partial_\eta \phi \partial_\eta u d\xi \end{aligned}$$



Transformed equation

$$\int_0^\infty \left(J_B^{-T} \nabla_{\xi,\eta} u(\xi, \eta) \right) \cdot J_B^{-T} \nabla_{\xi,\eta} \phi(\xi, \eta) |J_B| d\xi$$

$$= \int_0^\infty (h_\eta + \xi b) \partial_\xi \phi \partial_\xi u = h_\eta s(sU(s, \eta) - u|_{\xi=0})$$

$$-(\eta b - a) \partial_\eta \phi \partial_\xi u$$

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Transformed equation

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A function $u(x, \eta)$ satisfies the Pole Condition if for all η the Laplace transform $U(s, \eta)$ of $u(\cdot, \eta)$ has a holomorphic extension to the lower complex halfplane H .

Theorem (Schmidt, Hohage, Zschiedrich 1998):

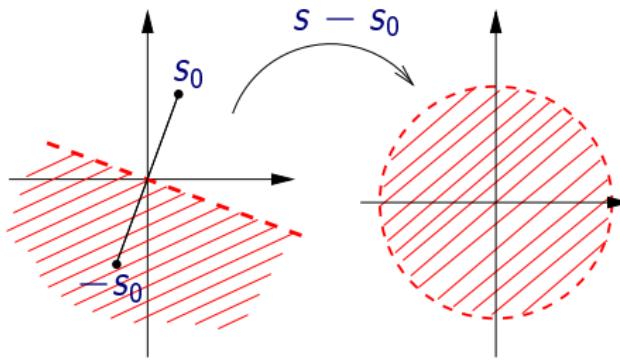
The Pole condition is equivalent to the Sommerfeld radiation condition:

$$\lim_{|r| \rightarrow \infty} \sqrt{r} (\partial_r u - iku) = 0$$



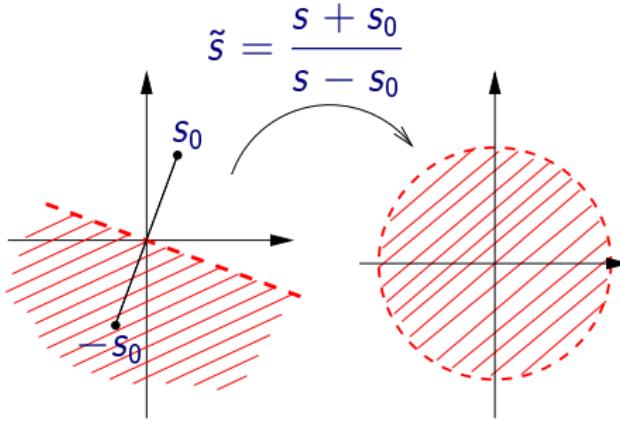
A Möbius transform maps the half plane H onto the interior of the unit circle.

$$\tilde{s} = \frac{s + s_0}{s - s_0}$$





A Möbius transform maps the half plane H onto the interior of the unit circle.



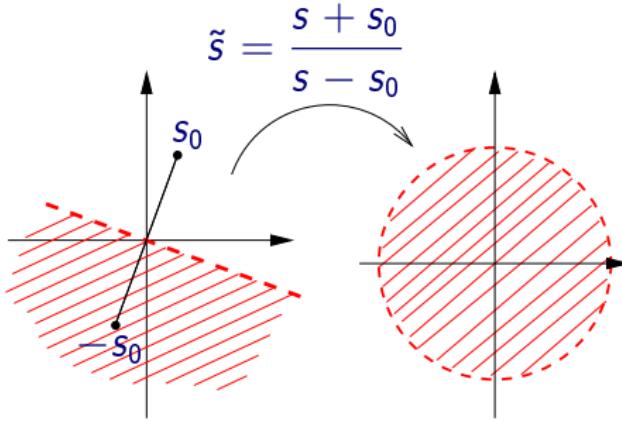
We have

$$\lim_{s \rightarrow \infty} s U(s) = u(0)$$

$$\lim_{\tilde{s} \rightarrow 1} s_0 \frac{\tilde{s} + 1}{\tilde{s} - 1} U(\tilde{s}) = u(0)$$



A Möbius transform maps the half plane H onto the interior of the unit circle.



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In the variable \tilde{s} , U is expanded into a power series.

$$U(\tilde{s}) = (\tilde{s} - 1) \left(\frac{u(0)}{2s_0} + (\tilde{s} - 1) \sum_{n \geq 0} a_n \tilde{s}^n \right)$$



Equations for the a_n

$$s(sU(s) - u_0) \leftrightarrow s_0^2 \begin{bmatrix} \frac{1}{2s_0} & 1 & & \\ \frac{1}{2s_0} & 2 & 1 & \\ & 1 & 2 & 1 \\ & & & 1 & 1 \end{bmatrix} \begin{bmatrix} u|_{\xi=0} \\ a_0 \\ a_1 \\ a_N \end{bmatrix}$$

$$s\partial_s(sU(s)) \leftrightarrow s_0 \begin{bmatrix} -\frac{1}{2s_0} & 0 & 1/2 & & \\ 0 & -1 & 0 & 1 & \\ \frac{1}{2s_0} & 0 & -2 & 0 & 3/2 \\ & & & & \\ \frac{n-1}{2} & \frac{-n}{2} & \frac{1-2n}{2} & & \end{bmatrix} \begin{bmatrix} u|_{\xi=0} \\ a_0 \\ a_1 \\ a_N \end{bmatrix}$$

$$sU(s) - u_0 \leftrightarrow s_0 \begin{bmatrix} -\frac{1}{2s_0} & -1 \\ \frac{1}{2s_0} & 0 & -1 \\ & 1 & 0 & -1 \\ & & & 1 & -1 \end{bmatrix} \begin{bmatrix} u|_{\xi=0} \\ a_0 \\ a_1 \\ a_N \end{bmatrix}$$

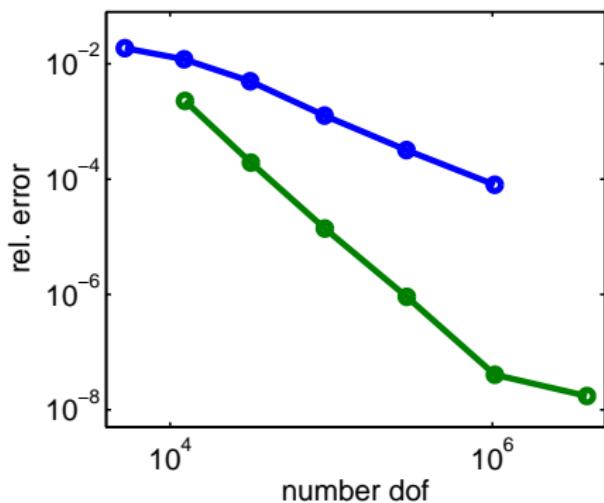
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$$\int_0^\infty \frac{1}{c + b\xi} u(\xi) \exp(-\xi s) d\xi = (b\partial_s + c)^{-1} U(s)$$

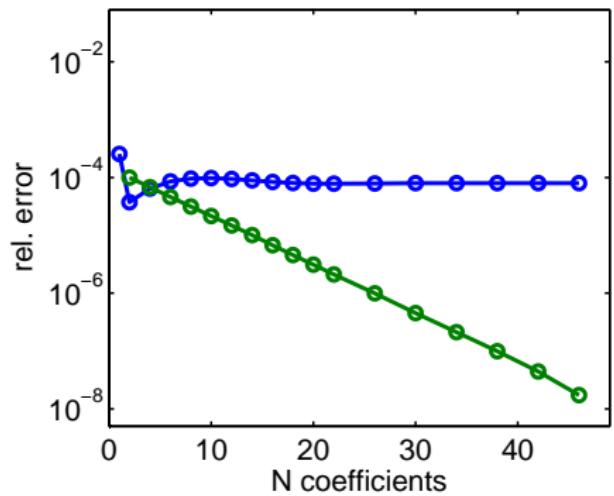
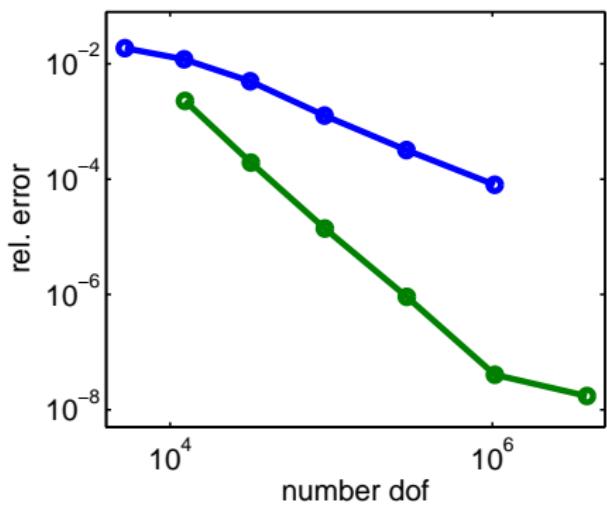
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Infinite element of size $N + 2$

Convergence



Convergence





- ▷ Extension to time-dependent problems
- ▷ Regularity of the exterior Helmholtz problem
- ▷ Is $\exp(-\xi s)$ “dense” ?
- ▷ Convergence theory